



# **VELA-RX 220V 500W**

Control unit for 1 or 2 devices. 110/240 VAC power supply, integrated RX 433.92 MHZ ISM, 2 wired inputs settable with button or switch. Pulse, On/Off, timer



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# WARNINGS

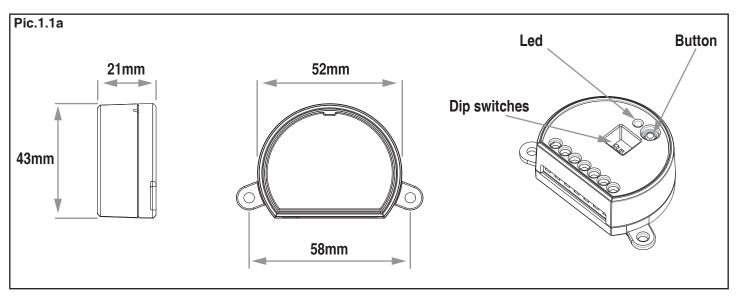
- Installation must be carried out only by qualified technicians in compliance with the electrical and safety standards in force.

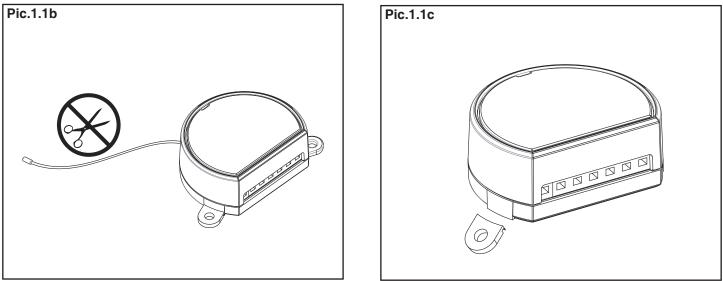
- All connections must be made with the power turned off.
- Use suitable cables.
- Do not cut through the aerial (picture 1.1b)
- A suitably sized disconnection device must be set up on the electric power line that supplies the product.
- Disposal of waste materials must fully respect local standards.

# **1 PRODUCT FEATURES**

# **1.1** TECHNICAL DATA

| Power supply                      | Mains 120-240 VAC                  |  |
|-----------------------------------|------------------------------------|--|
| Outputs                           | 2 contacts: 230 V max 500 W, 110 V |  |
|                                   | max 250 W for output               |  |
| Num. of programmable transmitters | 100                                |  |
| Radio frequency                   | 433.920MHz ISM                     |  |
| Protection rating                 | IP20                               |  |
| Operating temperature             | -20 +55 °C                         |  |
| Dimensions                        | 52x43x21 mm                        |  |

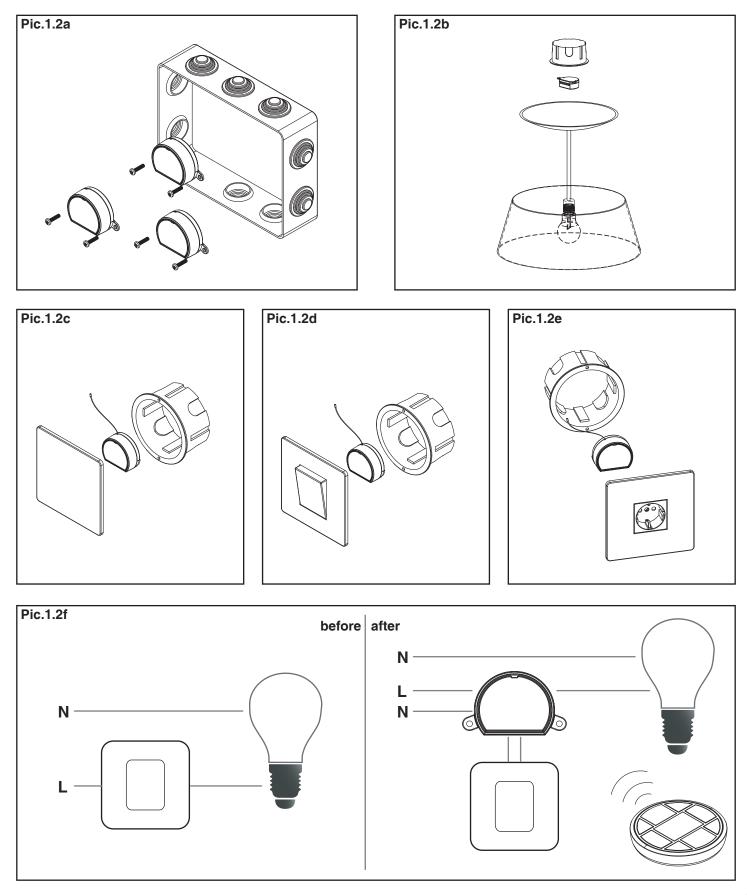




## **1.2** DESCRIPTION

Miniaturised electronic control unit for managing two devices via radio and wire, with either a button or switch. It is flexible and can be used in different applications thanks to the fact that the load can be controlled in monostable, bistable or timer (from 1 second to 60 hours) mode.

The ISM (industrial, scientific and medical) radio frequency band guarantees a long range, even through walls and ceilings.



# **2 ELECTRICAL CONNECTIONS**

This control unit comes set up for different types of connection that allow greater flexibility regarding the behaviour of the outputs and the types of inputs to adapt to various system configurations.

### **BEHAVIOUR OF OUTPUTS**

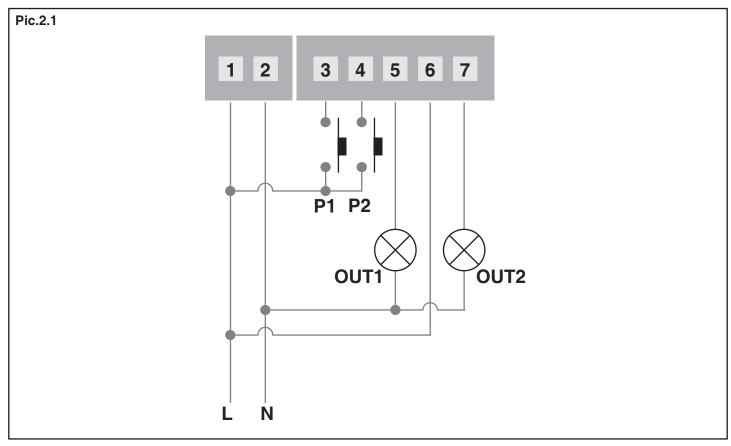
Depending on the type of load that you want to control, connections can be made that let you - control 2 loads powered by grid voltage (230 V max 500 W, 110 V max 250 W per output); paragraph 2.1. - have two potential-free output contacts; paragraph 2.2.

### **INPUT TYPE**

Thanks to the programming described in paragraphs 4.4 and 4.5, you can select whether the wired command is given by a button or a switch.

## 2.1 CONNECTIONS FOR LOADS POWERED BY THE GRID (230 V MAX 500 W, 110 V MAX 250 W PER OUTPUT)

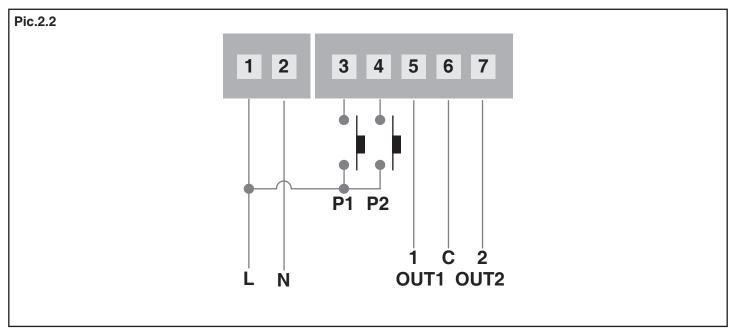
The following connection lets you control the loads powered by grid voltage, via radio and/or wire.



WARNING: Multiple loads can be connected to the same output by using parallel cabling. Multiple buttons can be connected to the same input by using parallel cabling.

## **2.2** CONNECTION FOR TWO DRY CONTACTS

The following connection lets you control two potential-free contacts by radio and/or wire.



**WARNING:** Multiple buttons can be connected to the same input by using parallel cabling.

# **3 USE OF THE CONTROL UNIT**

## **3.1** USE VIA RADIO

To control the loads via radio you must have compatible transmitters and therefore must carry out the association procedure, see paragraph 5.

The ways the transmitter is controlled depend on the setting of the outputs (see paragraph 4.1) and the model of transmitter used.

If the transmitter is of a generic type, its operation depends on the way it is programmed (see paragraph 5). If the transmitter is multifunctional, refer to the transmitter manual, to the paragraph entitled "commands sent by the transmitter", bearing in mind that:

Output set as monostable (see paragraph 4.1) = monostable device Output set as bistable (see paragraph 4.1) = on/off device Output

Output set as timer (see paragraph 4.1) = timer device

# **3.2** USE VIA WIRE

The device is set up to accept commands via wire from the button (or switches; see paragraphs 4.4, 4.5) in terminals 3 and 4. Should you want to control the load only via radio, it is not necessary to connect these devices for the control unit to work properly.

The behaviour of the inputs depends on the setting of the outputs (see paragraph 4.1). The following table shows the behaviours of the various keys:

|          | MONOSTABLE<br>RELAY           | BISTABLE<br>RELAY                            | TIMER<br>RELAY   | DEACTIVATED<br>RELAY |
|----------|-------------------------------|--|--|----------------------|
| INPUT P1 | close and reopen<br>contact 1 | change contact 1<br>status (closed,<br>open) | close contact 1 for the<br>time set<br>(see paragraph 4.2) | no action            |
| INPUT P2 | close and reopen<br>contact 2 | change contact 2<br>status (closed,<br>open) | close contact 2 for the<br>time set (see paragraph<br>4.3) | no action            |

# **4 CONTROL UNIT SETTINGS**

## 4.1 SETTING "OUT1" AND "OUT2" OUTPUTS

This process is used to configure the behaviour of the OUT1 (table 4.1a) and OUT2 (table 4.1b) output contacts.

#### Tab. 4.1a

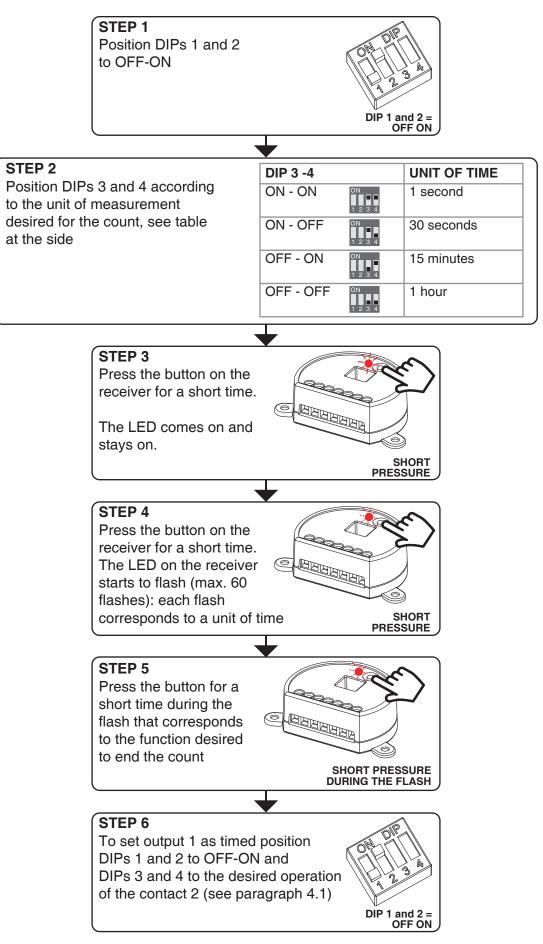
| CONFIGURATION<br>OF OUTPUT 1 |                     |                          |  |
|------------------------------|---------------------|--------------------------|--|
| DIP 1 - 2                    |                     | MODE                     |  |
| ON - ON                      | AT ALL SA           | Monostable<br>(pulse)    |  |
| ON - OFF                     | AT AREA             | Bistable<br>(On/Off)     |  |
| OFF - ON                     | ON DIP<br>1 2 3 4   | Timer<br>(see para. 4.2) |  |
| OFF - OFF                    | ON DIP<br>1 1 2 3 4 | Disabled                 |  |

| Tab. 4.1b                    |                   |                          |  |
|------------------------------|-------------------|--------------------------|--|
| CONFIGURATION<br>OF OUTPUT 2 |                   |                          |  |
| DIP 3 - 4 MODE               |                   |                          |  |
| ON - ON                      | OT PAR<br>1 2 3 4 | Monostable<br>(pulse)    |  |
| ON - OFF                     | OF THE            | Bistable<br>(On/Off)     |  |
| OFF - ON                     | ON DIF            | Timer<br>(see para. 4.3) |  |
| OFF - OFF                    | AN DR<br>1234     | Disabled                 |  |

## 4.2 SETTING "OUT1" TIMING

#### Default: 3 minutes

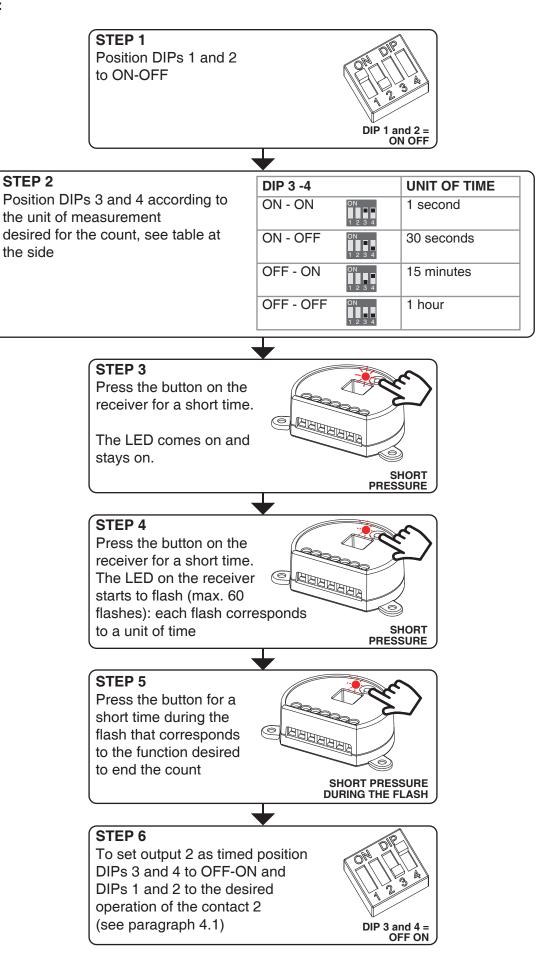
This process is used to set the time for which the "OUT1" contact stays closed if it is set on a timer.



## 4.3 SETTING "OUT2" TIMING

#### Default: 3 minutes

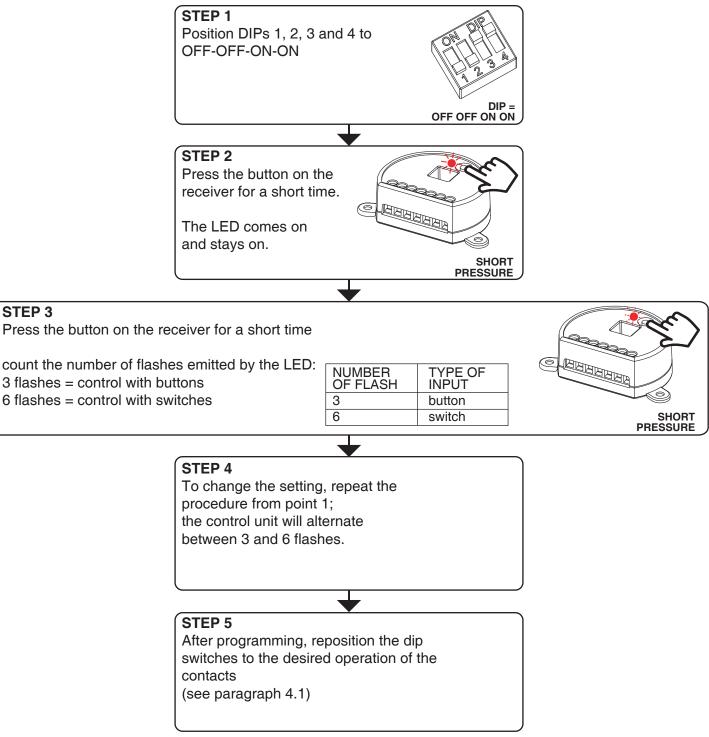
This process is used to set the time for which the "OUT2" contact stays closed if it is set on a timer.



## 4.4 SETTING TYPE OF INPUTS VIA WIRE "P1"

Default: Button

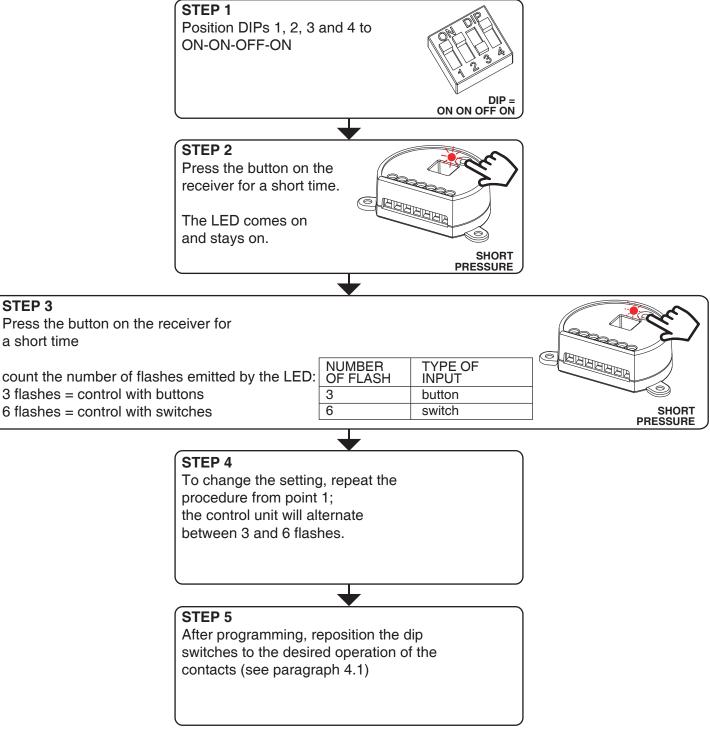
This procedure lets you choose the type of wired devices to command load 1 (connected on terminal 3, input P1). The devices can be set as buttons or switches.



## 4.5 SETTING TYPE OF INPUTS VIA WIRE "P2"

Default: Button

This procedure lets you choose the type of wired devices to command load 2 (connected on terminal 4, input P2). The devices can be set as buttons or switches.



# **5 - RADIO PROGRAMMING**

This procedure lets you programme multifunctional or generic compatible transmitters.

## WHICH REMOTE CONTROL DO YOU WANT TO ASSOCIATE WITH THE CONTROL UNIT?

### MULTIFUNCTIONAL TRANSMITTERS - MODELS AND CODES



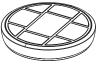
CODE: BLACK VELA TONDO 30

With multifunctional transmitters the transmitter control modes depend on the model used. Refer to the transmitter manual, to the paragraph entitled "commands sent by the transmitter", bearing in mind that it is an "On/Off" device.

## **GENERIC TRANSMITTERS - MODELS AND CODES**







**CODE:** WHITE VELA TONDO 6, BLACK VELA TONDO 6

With generic transmitters, the transmitter's control modes depend on the function associated with the key during the association procedure (see the following page).

The available function for the key are:

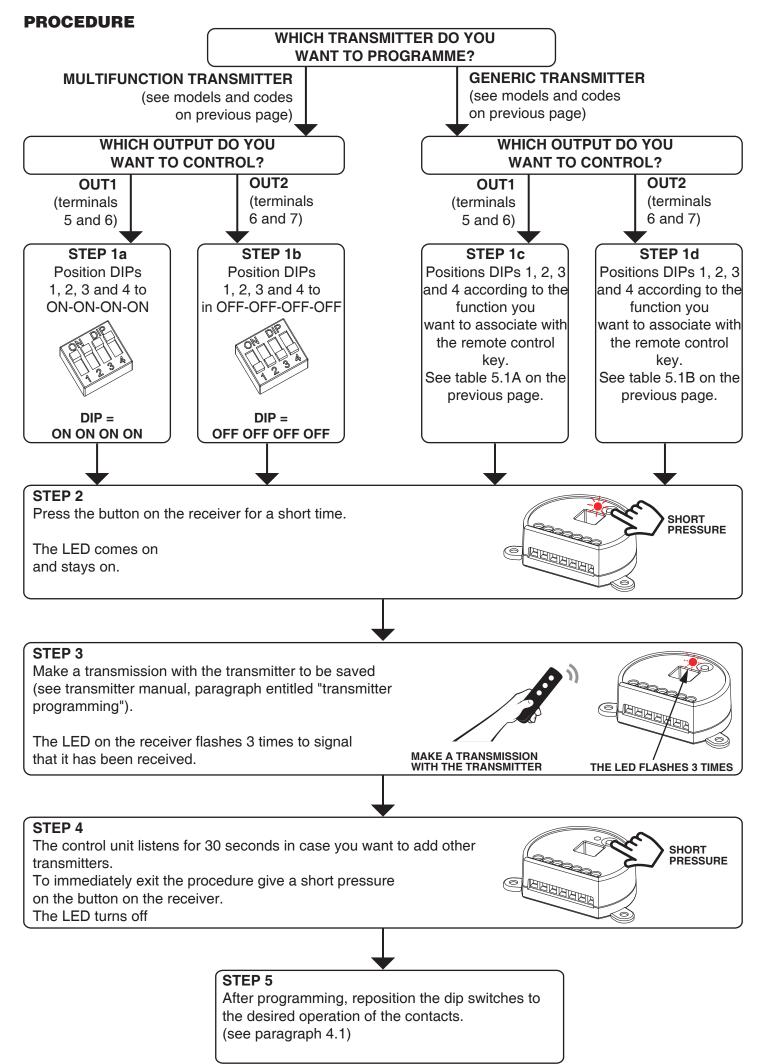
#### TABLE 5.1A

KEY FUNCTIONS OF THE GENERIC TRANSMITTER FOR OUT 1

### TABLE 5.1B

KEY FUNCTIONS OF THE GENERIC TRANSMITTER FOR OUT 2

| POSITION OF DIP IN "STEP 1c" | KEY      | POSITION OF DIP IN "STEP 10 | " KEY    |
|------------------------------|----------|-----------------------------|----------|
| OF THE PROCEDURE             | FUNCTION | OF THE PROCEDURE            | FUNCTION |
| DIP :                        | ON/OFF   | OFF OFF OFF OF              | ON/OFF   |
| ON ON ON ON                  | OUT1     |                             | OUT2     |
| OFF OFF OFF ON               | ON       | DIP :                       | ON       |
|                              | OUT1     | ON ON OFF                   | OUT2     |
| DIP :                        | OFF      | DIP :                       | OFF      |
| OFF OFF ON OFF               | OUT1     | ON ON OFF OFF               | OUT2     |



#### **FURTHER DETAILS**

### BEHAVIOUR OF OUTPUTS BASED ON THE FUNCTION ASSOCIATED WITH THE KEY

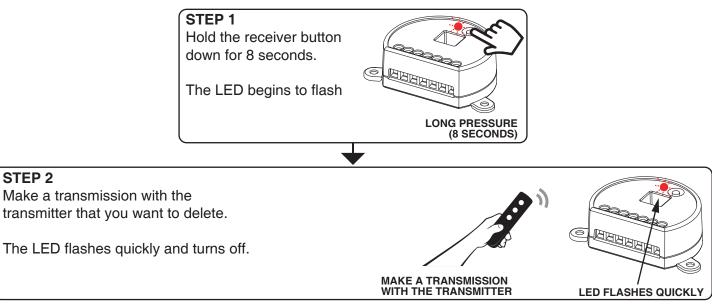
The column on the left shows the commands that can be programmed on the generic transmitter (see table 5.1), and the top row the output setting (see paragraph 4.1).

|                    |            | OUTPUT SETTING              |  |  |
|--------------------|------------|-----------------------------|--|--|
| FUNCTION<br>OF KEY | MONOSTABLE | BISTABLE                    | TIMER  |  |
| ON / OFF           | Pulse      | Change of status<br>of load | Close contact for the time set (see paragraph 4.2/4.3) |  |
| ON                 | Pulse      | Close contact               | Close contact for the time set (see paragraph 4.2/4.3) |  |
| OFF                | Pulse      | Open contact                | Open contact   |  |

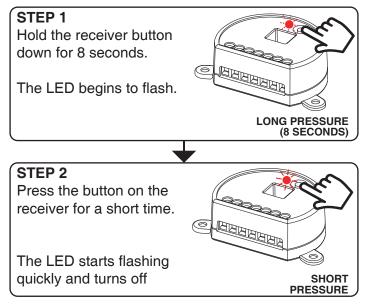
# **6 - DELETION OF TRANSMITTERS**

These procedures let you delete from the memory transmitters that have already been programmed.

## **6.1** DELETION OF SINGLE TRANSMITTER:



## **6.2** DELETION OF ALL THE SAVED TRANSMITTERS





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